

# Table of Contents

Information around the ROS.....	1
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# Information around the ROS

1) Check if the robintty driver is running. If it does not run start it.

2) Create a kermit configuration file. E.g. ".k0"

3) Fill .k0 with:  
set line /dev/robintty\_0  
set speed 115200  
set carrier-watch off  
set handshake none  
set flow-control none  
robust  
set file type bin  
set file name lit  
set rec pack 1000  
set send pack 1000  
set window 5  
connect

4) run "kermit .k0"

5) To stop kermit type "CTRL + \ + c"

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## Major updates:

-- MarkusJoos - 5 Apr 2007

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This topic: Sandbox > HowToRunKermit

Topic revision: r1 - 2007-04-05 - MarkusJoos



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