
Charge calibration and MC tuning of the SST

Giacomo BRUNO

UCLouvain

27 February 2010



<http://cp3.phys.ucl.ac.be/>



UCL

Université
catholique
de Louvain

-
- Detector response (in ADC) must be equalized in data to correct for instrumental effects that are absent in MC
 - procedure uses tracks from MB events
 - Physics effects are corrected too!
 - Result: $\{C_{data}^{eq}\}$
 - one per APV
 - No dimensions
 - Corrections are such that MPV for the chosen calibration sample is **300 ADC/mm**
 - These corrections are regularly uploaded to DB

-
- Align equalized data (ADC) and “raw” MC (MeV) to the Bichsel prediction: $MPV=f(p)$ [MeV] at a given pathlength
 - Procedure needs a sample of tracks with fixed pathlength
 - Result: $\{C_{data}^{bi}\}$ [MeV/ADC] and $\{C_{MC}^{bi}\}$ [no dimensions]
 - Data and MC corrections: one per η -R ring of modules
 - These corrections are computed once and for all (can be stored on DB)
 - These corrections will be used by applications that need to know the physical energy deposits (e.g. dE/dx)

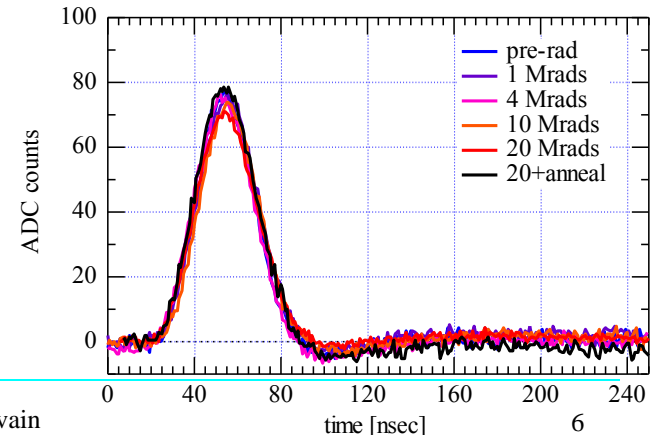
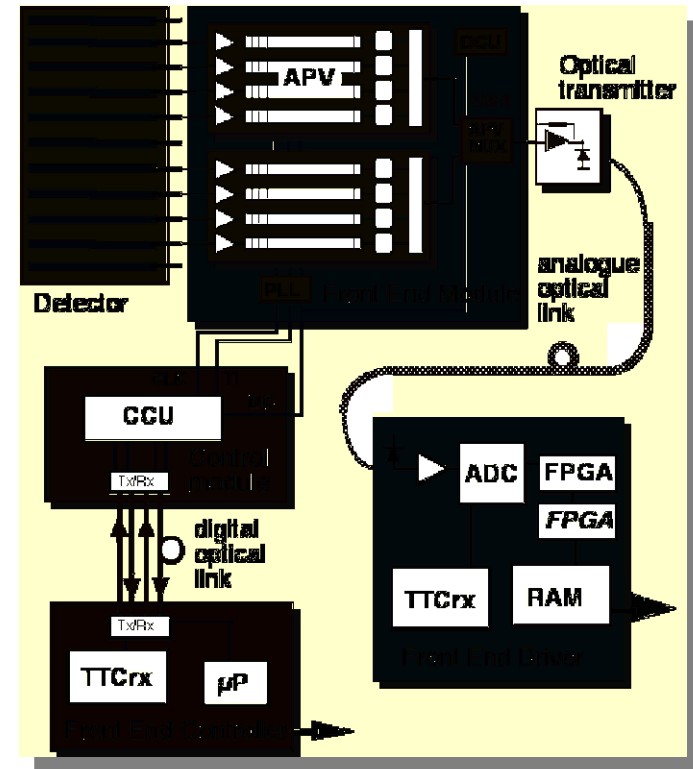
- Conversion of MC response to ADC

- Use: $MC_{\text{raw}} [\text{MeV}] * \{C_{\text{MC}}^{\text{bi}} * 1 / C_{\text{data}}^{\text{bi}}\} [\text{ADC/MeV}]$
- This correction guarantees that MC gives an answer in ADC that corresponds to equalized data {by definition: MPV = 300 ADC/mm on MB sample}
- This correction is also computed once and for all, because data is always equalized to an absolute level.
- We solve also the issue of MC productions having to handle detector instabilities over time !
 - E.g. will not need to ask ourselves with which gain corrections should we make the 2011 MC production

BACK-UP SLIDES

Charge response

- Charge response in silicon strip detectors can be different from channel to channel due to a variety of reasons
 - **Physics:**
 - particle momentum and type
 - **Instrumental:**
 - Particle pathlength in silicon
 - incident angle
 - Module thickness
 - Defects/damage on silicon wafers, implants, connections
 - Sampling time (also dependent on TOF)
 - Configuration/Response of electronic and optical components (APV, Laser, fibers)
 - Zero Suppression
 - Module layout (thickness, pitch, strip dimensions)
 - Incident angles (parallel and orth. To strips)
- Deviations from linearity and absolute dE/dx scale must also be known



Charge calibration

G. Bruno, L. Quertenmont – UC Louvain

Charge calibration use cases

- Track reconstruction

- Cluster building

- Condition applied: $\sum S_i > n\sqrt{\sum N_i^2}$;[S==signal, N==Noise, n=5 (def)]
 - Whereas, the individual channel thresholds need no correction neither on S_i , nor on N_i

- Position and error of reconstructed hits

- Currently estimated using the charge ratio between different strips in a cluster

→ Equalization at the level of a single module is enough unless global parameterizations not just based on ratios are used

- dE/dx technique

- Particle identification (CMS Note 2008/005)

- Low momentum standard particles (CMS AN-2007/021)
 - High momentum hypothetical heavy stable charged particles (HSCP; CMS AN 2007/049)

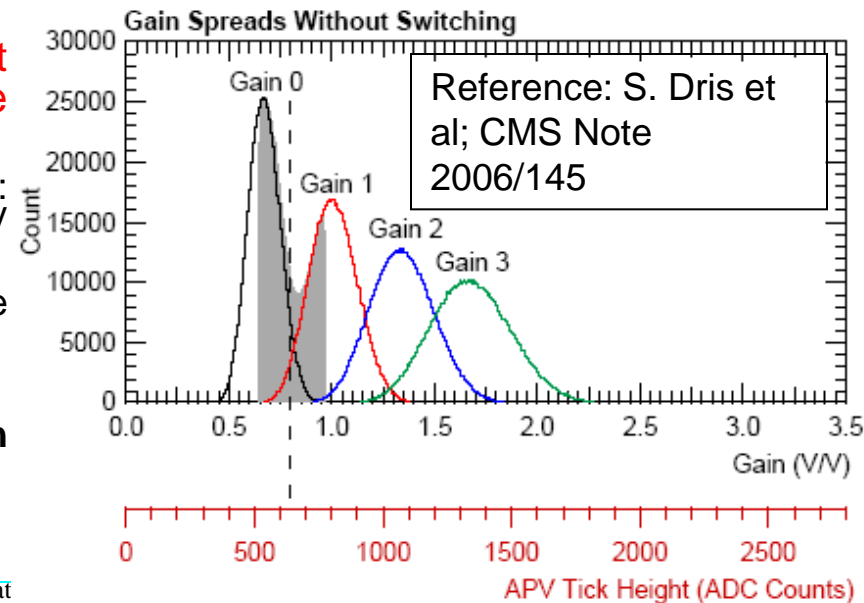
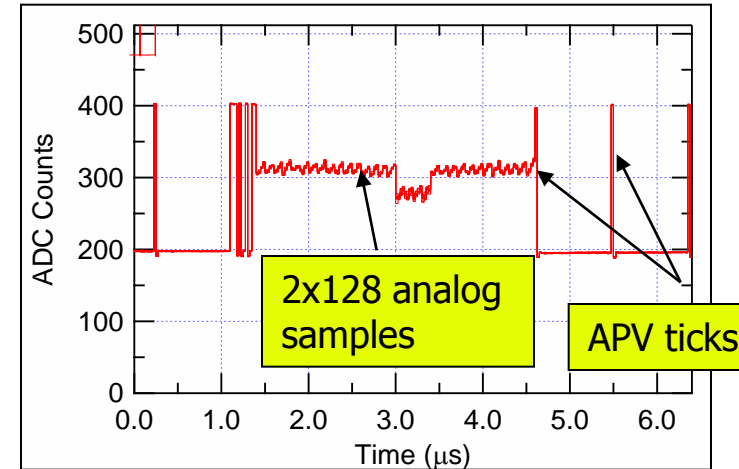
- Mass measurement

- Heavy exotic particles

→ Global calibration across modules is necessary

Calibration signals: tickmarks

- “Tickmark” signals
 - can be produced by each APV
 - Tick height is full digitizer (FED) dynamic range
 - $\pm 5\%$ variation from APV to APV (M. Raymond, *et al.*, CERN/LHCC/2005-038, pp. 453-457, 2005)
- Response equalization is performed to some extent in the hardware configuration
 - Feed tick mark signal produced by each APV into FED.
 - see response in terms of ADC counts.
 - Choose the one in four available values that brings the response closest to a reference value.
 - One discrete parameter (Laser Driver gain: 0,1,2,3) can be set in the AOH (one per APV pair)
 - Distribution is non gaussian after hardware gain optimization
 - **Intrinsic precision of the method $\sim 15\%$**
 - **Plus contributions from all effects to which the method is insensitive**



Charge calibrat

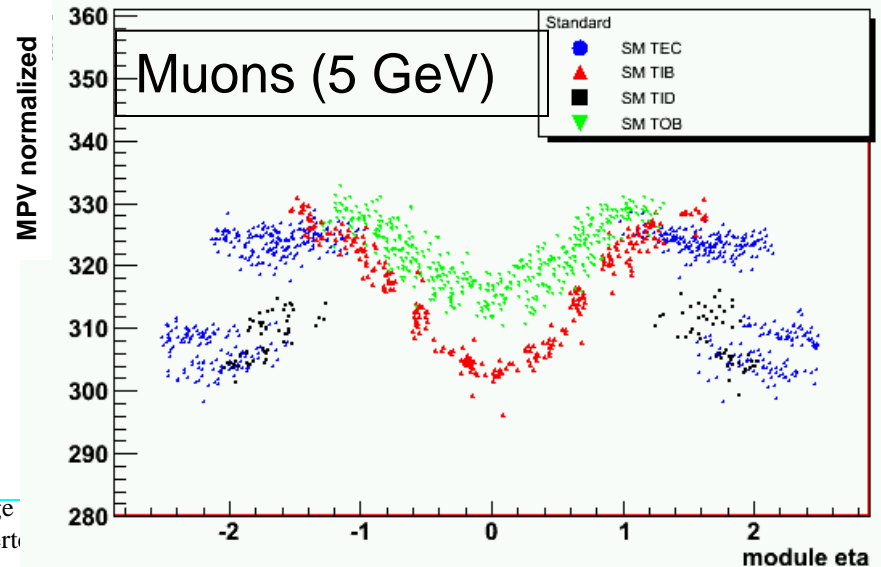
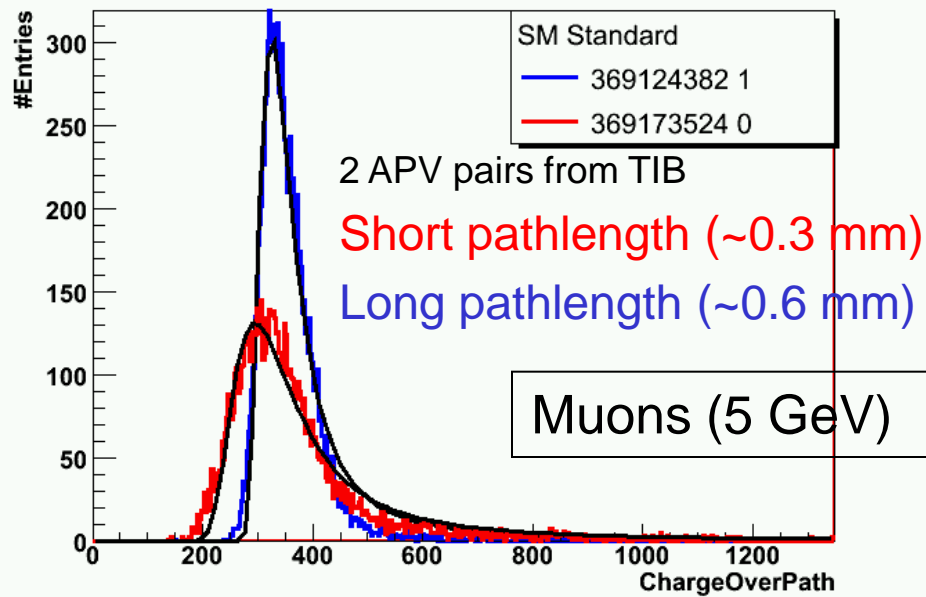
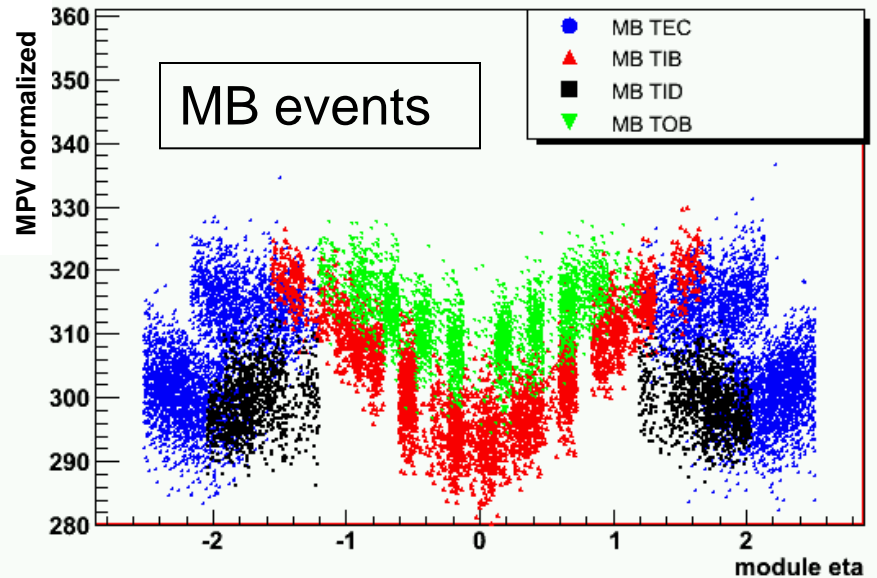
G. Bruno, L. Quertenmont – UC Louvain

Calibration with particles

- Goal
 - Correct for residual miscalibration of tick mark method ($\pm 5\%$ + any effect on amplification chain before AOH)
 - In addition, absolute mass scale determination and linearity crucial for special particle id (e.g. Heavy Stable Charged Particles)
- Method:
 - Take all clusters associated to tracks (cosmics or MB)
 - Normalize charge to thickness traversed
 - Produce a charge distribution for each APV pair
 - Fit to a Landau and use Most Probable Value (**MPV**) to compute the correction

Normalized MPV distributions

- Large MPV variation (more than 10%)
 - Clear correlation with pathlength through modules
 - Explained by dependence of MPV on pathlength
 - $MPV \sim Ax + B \ln x$ [PDG]
 - $FWHM / MPV = [15\%, 50\%]$
 - MB give wider dispersion than monoenergetic muons at fixed η
 - Explained by different spectrum/typical pathlength (due to stronger bending) for modules at different R



Charge calibration

- Must choose a conventional calibration point
 - Equal response guaranteed only at this point
 - Definition of equal response: “MPV of normalised charge distribution is equal to Reference Value”
 - Landau width at calibration point will vary significantly (FWHM / MPV) \approx [15%,50%], depending on
 - Geometrical location of the module (pathlength)
 - chosen particle type/momentum (pathlength and specific ionization)
 - Away from calibration point:
 - Normalized MPV and Width will change with respect to Ref. Value
 - In addition, for 2 modules in different $[\eta, R]$ “rings” they will shift differently
 - Reasons:
 - Particle type (different specific ionization)
 - Particle momentum (different pathlength and specific ionization)
- Scenario ‘A’ (CMS start-up)
 - Use all tracks with $p > 1$ GeV from MB events
 - O(1 M) events are enough
 - 1 day of MB data taking at 10 Hz and 14 TeV

Particle identification

Assumption

- All dE/dx measurements (normalised cluster charge) of a given track come from a single Landau distribution that only depends on the particle m and p (measured).

Identification principle

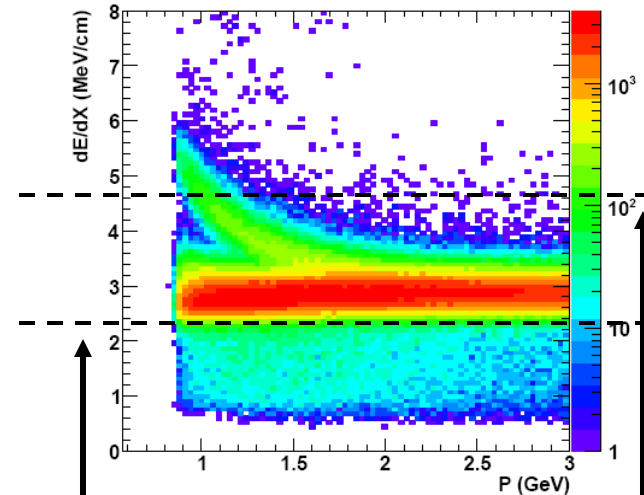
- estimate the MPV with the ~ 10 dE/dx measurements.

Method

- Obtain dependence of dE/dx estimator and dispersion vs p
- Protons and, hopefully, kaons will be distinguishable in specific p intervals.
- HSCP will feature a striking pattern.
- Identify particles on a simple cut basis (p dependent)

Limitations

- dE/dx measurements do not come from the same Landau
 - $\sim 5\%$ variation on MPV from calibration (MB p spectrum)
 - $\sim 10\%$ variation in points far from the calibration point (MIPs), due to different shift of MPV with pathlength and specific ionization
 - Measurements with longer pathlength must be given higher weight (they come from thinner and almost Gaussian shaped Landau distributions)
- **Cut-off of 255 ADC counts**
 - $\sim 5\%$ on MPV in high pathlength region (calibration fit bias)
 - Landau tail shape affected differently
 - Critical for HSCP id (non-bent tracks \rightarrow small cluster size)



255 ADC counts for
pathlength = 1 mm

255 ADC counts for
pathlength = 0.5 mm

Calibration Scenario 'B'

- Calibration point
 - Align normalized MPVs for tracks of relatively high p , say [10-15] GeV
 - Can be any (isolated) track and later even identified muons (combined Tk-Mu muon id needed)
- Features
 - + insensitive to p spectrum variations (5% effect)
 - + high p SM tracks give well defined point
 - straight tracks: can define an “intrinsic” pathlength for each module
 - Lots of overlapping effects from MB eliminated
 - + can fully exploit a likelihood based method (high- p SM-particle incompatibility) in HSCP search (see next slide)
 - Potentially more powerful than currently investigated methods
 - Makes full use of all information available (Landau MPV, shape...)
 - Will soon investigate its potential

Statistics?:

- Step 1: intercalibrate with MB events all modules in a given $[\eta, R]$ “ring”
 - ϕ symmetry: same geometrical data, same illuminating spectrum.
 - 1 M events are enough (1 day of MB data taking at 10 Hz)
- Step 2: Intercalibrate rings using monoenergetic muons
 - O(100) Charge distributions to populate (instead of 33k)
 - ~10 k high p tracks needed

More advanced Particle Identification

- HSCP search
 - Scenario 'B' calibration
 - Obtain normalized charge distributions vs pathlength
 - Possibly as a function of cluster size/pitch (if strong dependence exists – to be investigated)
 - For each dE/dx measurement of an HSCP candidate compute probability from corresponding charge distribution
 - Build likelihood from all measurements
 - Apply muon-incompatibility cut
- Low p particle identification
 - Same as above.
 - In addition, need pure samples of protons and/or kaons
 - Obtain charge distributions as a function of pathlength for different $\beta\gamma$ values
 - Build likelihood from all measurement to test different mass hypothesis

Outlook

- Particle Physics aims at pushing forward our fundamental comprehension of the Universe we live in
- It prepares the ground for far-future Applied Science
- It already pushes applied science beyond its frontiers