

# Geometry framework status

---

- **Definition**
- **Detector geometry service**
- **Detector Element Approach**
  - Outline
  - New software
  - Implications for users
  - An example
  - Requirements from sub-detector SW
- **Summary**
- **Work in progress**

**Juan P. Palacios**  
**CERN**

# Working definition

---

- **Provide users of detector geometry description with geometrical information derived from two places:**
  - Nominal alignment of all the sub-components of LHCb
    - Placements of logical volumes within hierarchy (XMLDDDB)
  - Deviations from the nominal alignment
    - Thought of as conditions: could change
- **Provide mechanism for users to modify the deviations from nominal alignment for a given sub-component**
  - ensures modifications are propagated coherently to the geometry description
- **Provides a mechanism to write a new set of deviations to the conditions database**

**The very basic functionality to allow for alignment algorithms to work**

# Detector geometry service

---

- Accessible through `DetectorElement::geometry()` methods
- Return `IGeometryInfo*` which has local to global and global to local transformations and a host of other services
  - See [http://lhcb-release-area.web.cern.ch/LHCB-release-area/LHCB/doc/html/class\\_i\\_geometry\\_info.html](http://lhcb-release-area.web.cern.ch/LHCB-release-area/LHCB/doc/html/class_i_geometry_info.html)
- Incorporate misalignments into `IGeometryInfo`
  - Each detector element will now have ideal and misaligned geometry information
  - User code should remain the same

# Detector element approach

---

- **Basic idea:**
  - Make transformations accessible to the Detector Element and let it do the work
- **Two limits:**
  1. **ALIGNMENT:** One detector element per alignable object. Needs basically one transformation.
  2. **OTHER CONDITIONS (?):** A detector element that knows enough about its PVolume daughters (and their daughters, and their daughters' daughters, and their daughters' daughters' daughters, and ...) to assign the correct transformations to each

# The basic idea

---

- **One detector element per alignable object**
  - Can be simply delemfer in XML and default detector element
  - VELO example: whole VELO, detector halves, r- $\phi$  pairs, individual sensors
- **One “delta” transformation matrix for each detector element: *conditions catalogue + AlignmentCondition***
  - Catalogue with one to one mapping to alignable objects
  - Paths point to plain XML file or address on conditions data store interface
  - Delta held in new specialised *AlignmentCondition* class
- **New *IGeometryInfo* implementation:**
  - Makes own AlignmentCondition object from catalogue path

# New IGeometryInfo

---

- **Handles both ideal and delta transformations:**
  - DetectorElement public interface stays the same.
  - IGeometryInfo toGlobal and toLocal methods now deal with combined ideal + delta transformations
  - Methods to get ideal geometry have been added
  - Possible for users to update delta matrix
  - Easy to “refresh” state of new GeometryInfo. All caching controlled from one method, aptly named **cache()**
  - GeometryInfo accesses CondDB (or test XML file), generates all necessary matrices
- **Implementation ready and tested with XML conditions catalogue**

# What does GeometryInfo do?

---

- **Constructor uses path to get AlignmentCondition**
- **Scans down tree picking up parent transformations**
  - Iterative procedure finding GeometryInfos of support detector elements
  - Stores ideal and delta transformations for each level in vectors
    - Allow to re-calculate after updates
  - Combines ideal matrices to get ideal case local to global
  - Combines all matrices to get local to global with misalignments
- **“Local” misalignment matrix can be updated by user**
  - Re-calculates “global” matrix automatically
  - At the moment this is de-coupled from automatic update mechanism

# Conditions catalogue

---

- **Added “condition” attribute to geometryinfo in structure.dtd**

- Only necessary to add an

```
<geometryinfo condition="somePath" />
```

in each `<detelem .... />` definition

- Then store the condition somewhere:

```
<condition classID="6" name="somePath">  
  <paramVector name="dPosXYZ" type="double"> 0. 0. 0.</paramVector>  
  <paramVector name="dRotXYZ" type="double"> 0. 0. 0.</paramVector>  
</condition>
```

- **At the moment, test XML files**
- **Can store as XML strings in CondDB: keep format the same!**



# Creation of an AlignmentCondition

---

- **At the moment, via XML and dedicated “converter”**
- **classID = 6 maps to XmlAlignmentConditionCnv**
  - This is a little template which simply instantiates the right kind of condition
- **AlignmentCondition has access to the parameters and constructs the matrices**

```
<condition classID="6" name="/dd/Conditions/LHCb/myDetector/Module67">  
  <paramVector name="dPosXYZ" type="double"> 0. 0. 0.</paramVector>  
  <paramVector name="dRotXYZ" type="double"> 0. 0. 0.</paramVector>  
</condition>
```

- **GeometryInfo accesses condition via data service:**

```
SmartDataPtr<AlignmentCondition> cond(datasvc(),  
  "/dd/Conditions/LHCb/myDetector/Module67");
```

# How to use misalignment information

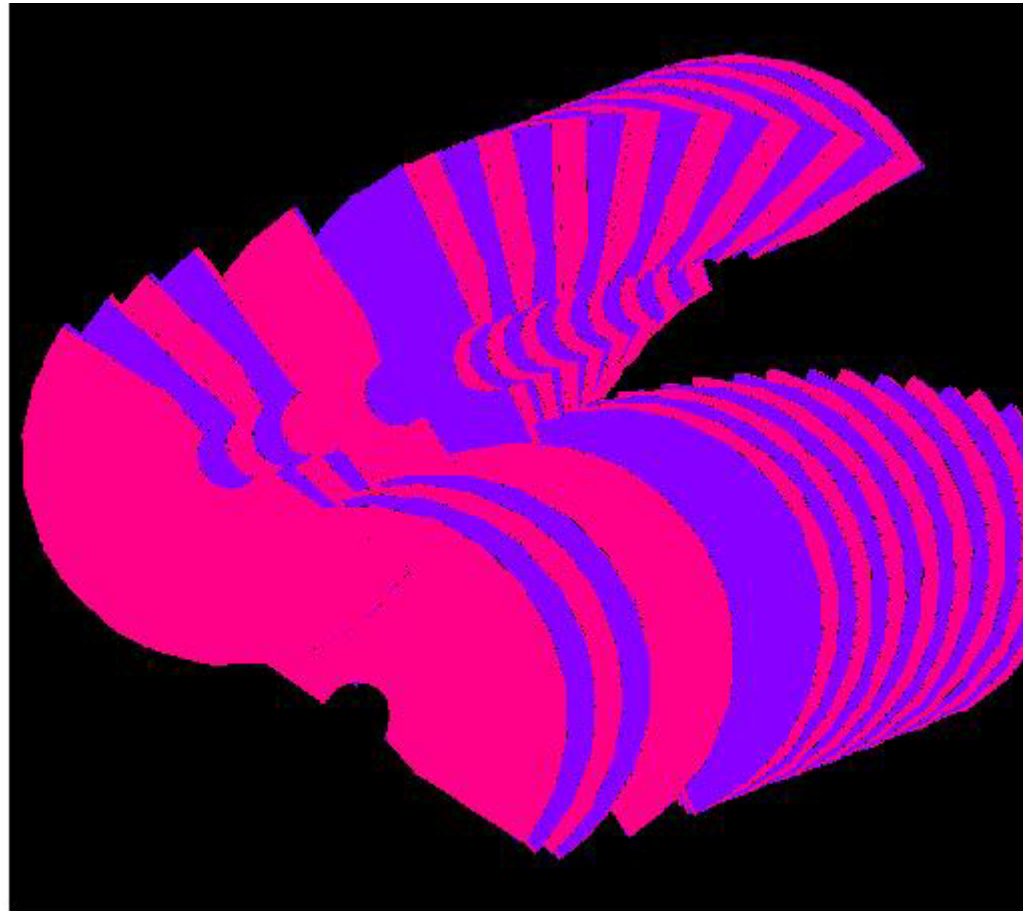
---

- **Keep currently used DetectorElement interface**
  - DetectorElement::geometry() still points to IGeometryInfo
  - IGeometryInfo handles ideal and misaligned geometry
  - Standard transformation methods deal with misaligned geometry
    - User code will automatically get misaligned geometry transformations if unchanged
  - New methods allow to perform ideal transformations
  - Delta matrix also available – and can be modified

**CODE USING DetectorElement::geometry() WILL NOW GET MISALIGNED GEOMETRY!**

# An example of a misaligned detector

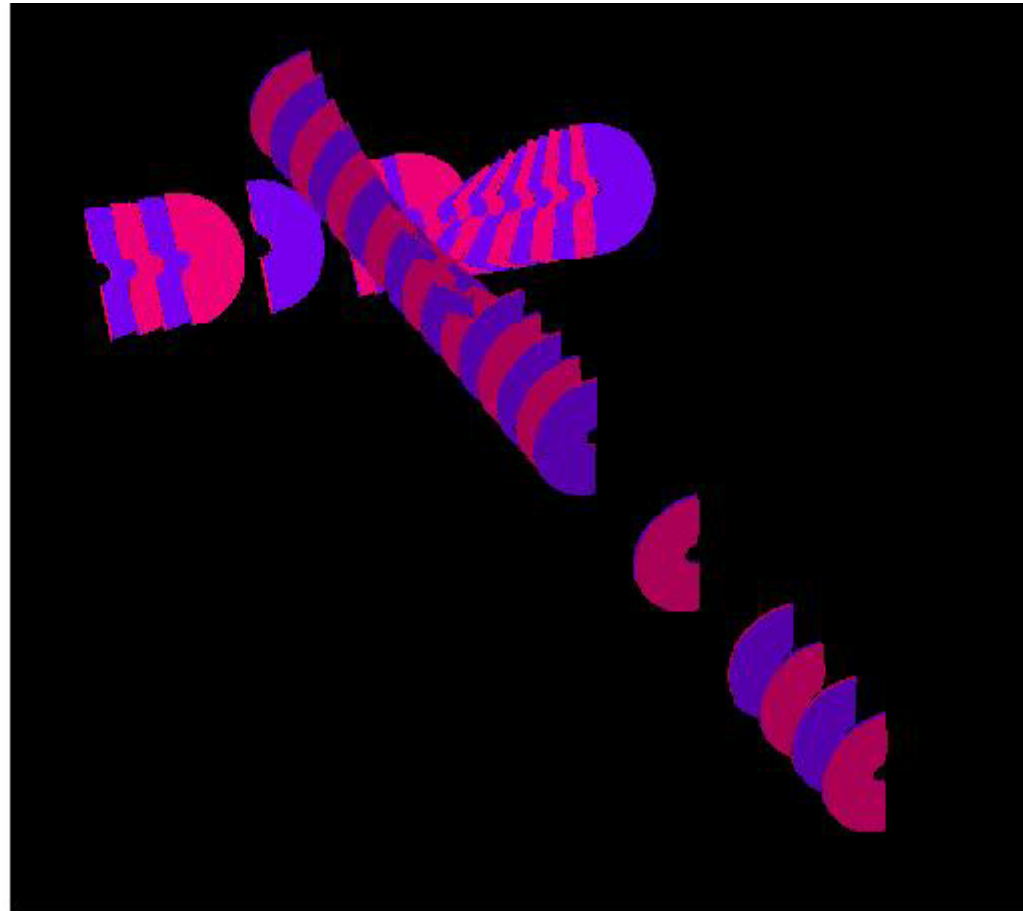
---



**Open VELO with Z-dependent  $\phi$  misalignemnt from test XML conditions file**

# Another example of a misaligned detector

---



**Open VELO with Z-dependent  $\phi$  misalignemnt and rotation about X axis. From test XML conditions file**

# Requirements from detectors

---

- **A detector element per alignable object**
  - Must have path to an alignment condition
  - In current scheme this means a condition in the XML <geometryinfo /> definition of the detector element. This contains the correct path in the data store
- **A catalogue of conditions with one-to-one mapping to detector elements**
  - In absence of condition identity matrix is created so current XML descriptions still work for ideal
- **A geometry description where the alignable objects can be associated to an LVolume**
  - Actually, an ASSEMBLY might do, but can't say for sure yet!
- **A good knowledge of where and how geometry information is cached: more of this next week!**
  - But basically, should strive to do all caching from a small number of methods as they will have to be registered somewhere

# Summary: what is there

---

- **XML conditions catalogue**
  - Changes to structure.dtd condition definition and XmlBaseConditionCnv to allow for conditionrefs inside conditions
  - VELO example tree of references
    - Working for now with dummy XML alignment parameter vectors
    - Populating CondDB with XML strings of the same format seems trivial
- **New GeometryInfo class**
  - New implementation
  - Instantiated in DetectorElement from XmlBaseDetElemCnv
  - Modifications to both the above to pass condition address
- **AlignmentCondition class**
  - Assigned **classID 6** and “Wrote” XmlAlignmentConditionCnv
  - Instantiated in GeometryInfo using path to get alignment parameters from (XML based for now) data store.

# Work in progress

---

- **Use of CondDB data store interface**
  - Conditions retrieval
  - Updating conditions in data store and DB
- **Incorporate update manager**
  - Mechanism to update necessary cached info after a condition has changed.
- **Update of conditions on the fly:**
  - Implemented, needs testing
- ~~**Visualisation**~~
  - ~~Could we see move volumes in Panoramix? Good for debugging/interpreting~~
- **Related note: what about simulation? Can the misalignments be used there?**

*Have necessary code from Marco.  
Incorporate this week.*

**DONE**

**In progress. Gauss crashing and don't know why yet**