

EoC Full Chain T0 Performance Measurements

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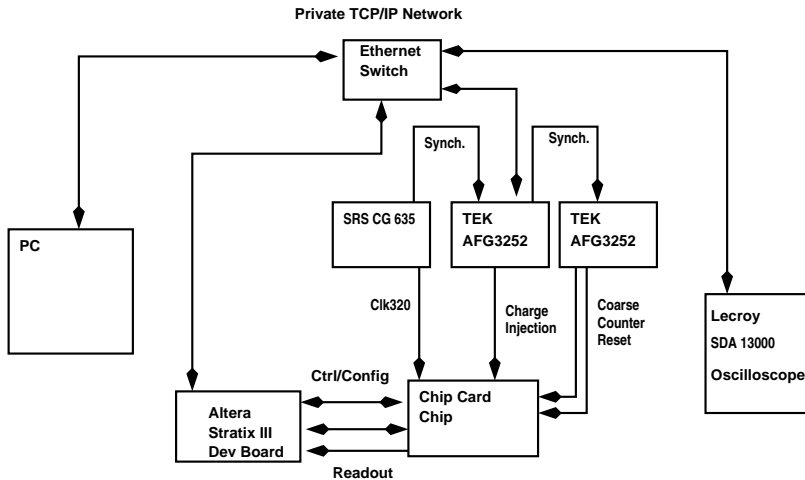
Test Setup, Parameters and Methodology

T0 Definition and Extraction

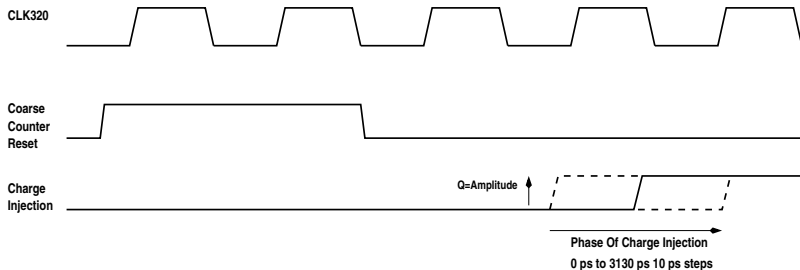
Experimental Results

Summary

Digital Measurement Set Up



Timing Diagram



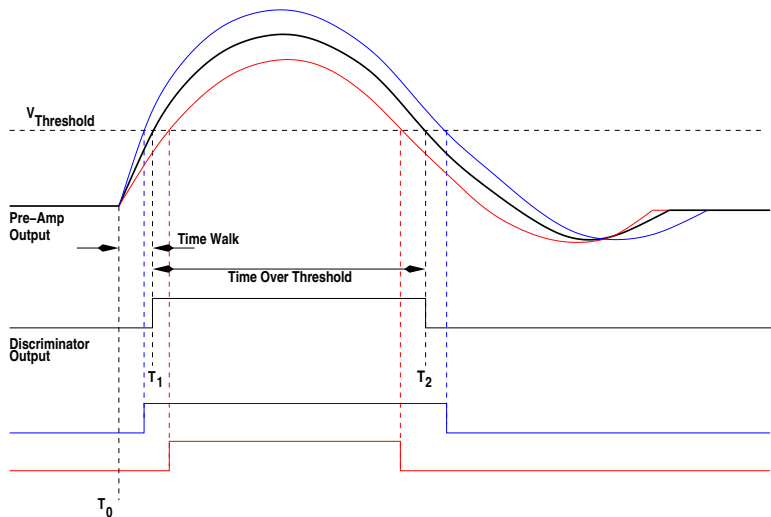
Parameter Space and Data Treatment

- ▶ Threshold set to 0.7 fC
- ▶ Charge Injection Duration set to 2.5 ns
- ▶ Charge injected 1.0fC, 1.2fC... 2.0fC, 3.0fC... 10.0fC
- ▶ Phase of injection swept from 0ps \rightarrow 3130 ps
 - ▶ 314 settings
- ▶ repetition rate 10kHz
- ▶ coarse counter reset synchronously
- ▶ \sim 20000 time stamps per point
 - ▶ first 10000 used for calibration
 - ▶ second 10000 used for measurement
- ▶ results for a single main array pixel presented
- ▶ TDC nonlinearity correction used for T1 and T2
 - ▶ Fine time = $N * (T_{clk}/32)$ replaced with LUT with bin centres

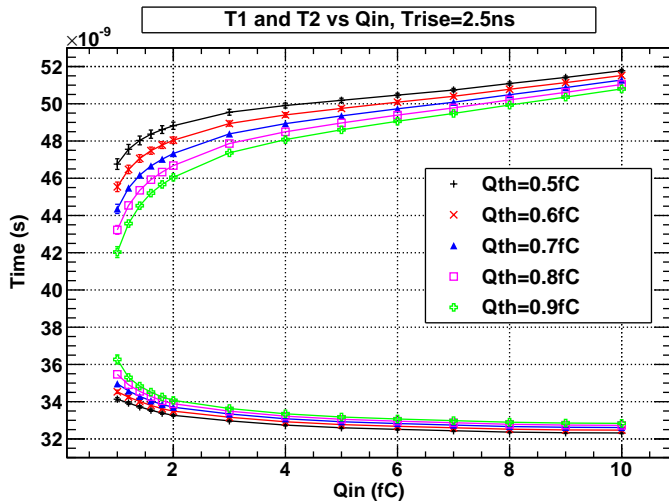
Working Point

- ▶ Digital VDD Set to 1.5V
- ▶ DLL Clock at 320 MHz
- ▶ Readout Clock at 320 MHz
 - ▶ Both are always present
- ▶ RxClkBias $\sim 300 \mu A$
- ▶ Temperature:
 - ▶ Lab ambient temperature $\sim 22^\circ C$

Time Over Threshold Time Walk Correction



T1 and T2 Timewalk: Test pixel measurements



Correction Methodology

- ▶ Necessary to define a pixel dependent, Q – *invariant* quantity
- ▶ Absolute calibration step still required
 - ▶ e.g. transmission line propagation delay

$$T_0 = T'_0 - T_{ac} \quad (1)$$

- ▶ Where T_{ac} is the absolute calibration step and depends on pixel location
- ▶ T_{ac} may be determined to arbitrary precision.

Correction Methodology

Define T'_0 as:

$$T'_0 = T_1 - k(TOT) * (T_2 - T_1) \quad (2)$$

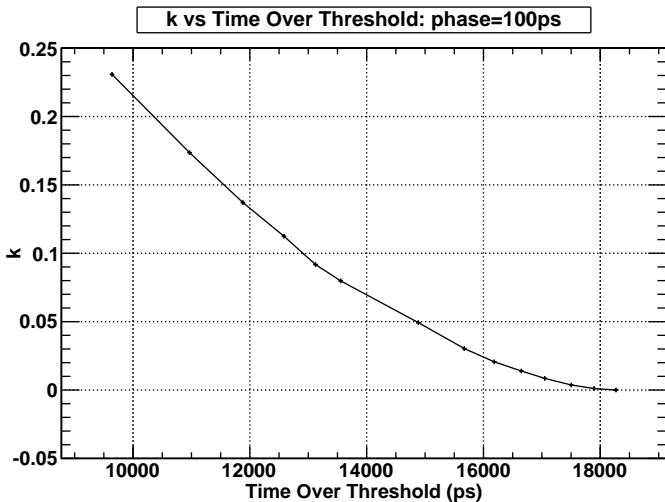
the k are functions of time over threshold. In practice a spline parameterisation is used to provide a continuous implementation of the discrete measurement points

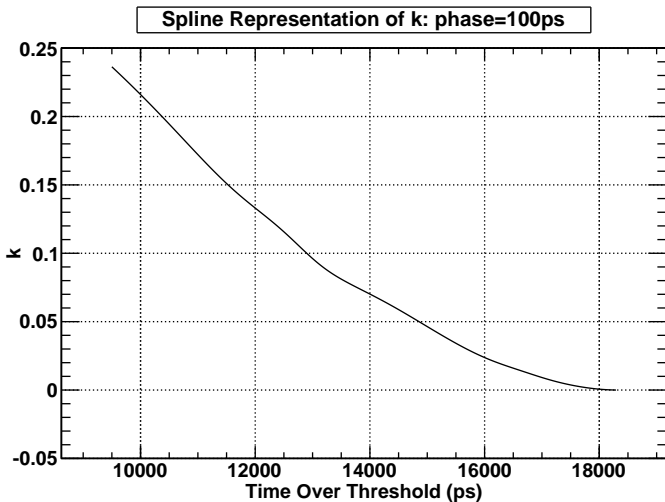
k can be calculated:

$$k = \frac{T_1 - T'_0}{T_2 - T_1} \quad (3)$$

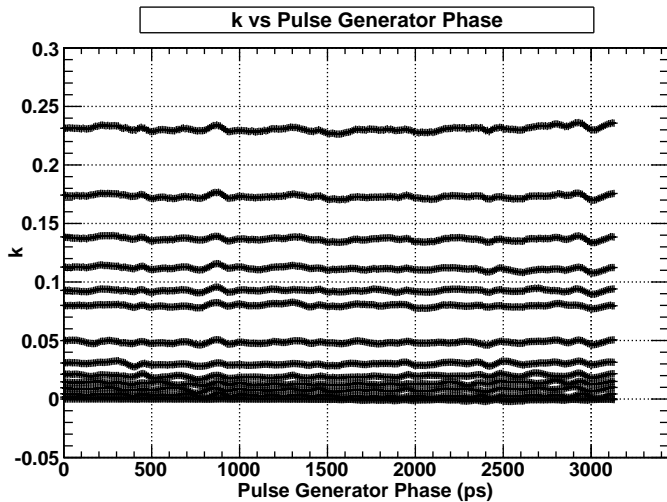
for Q , Q_{th} , Pixel and T_{rise} and Phase.

- ▶ For this study, T'_0 was taken as $\langle T_1(10fC) \rangle$

Typical k 

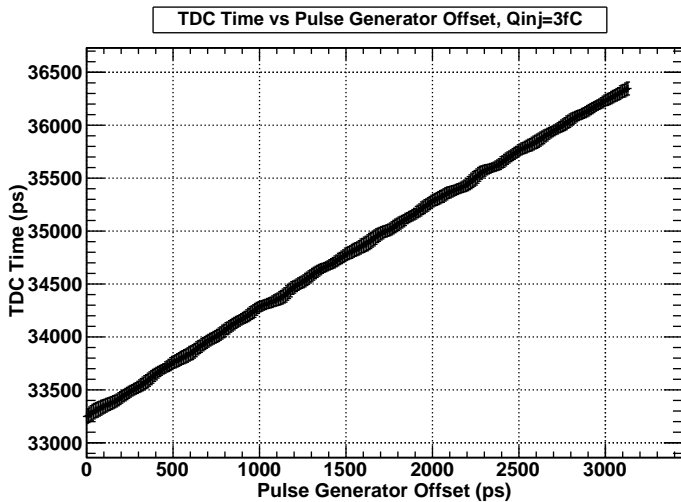
Spline Parameterisation of k 

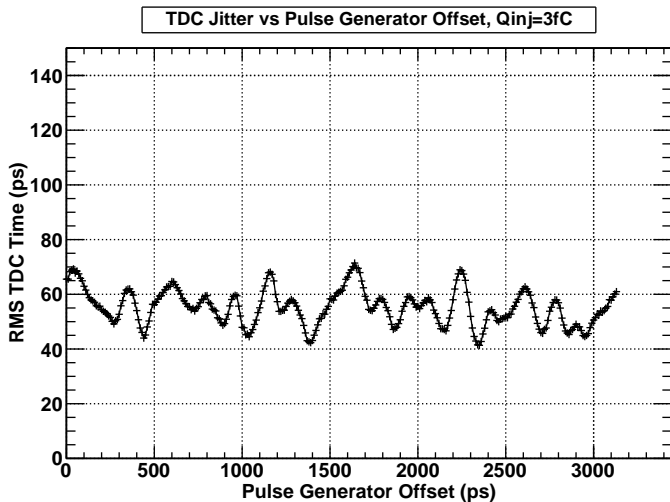
k vs Phase

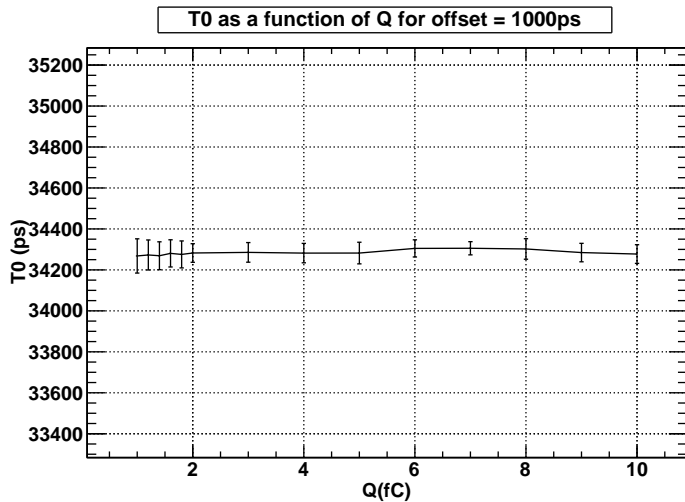


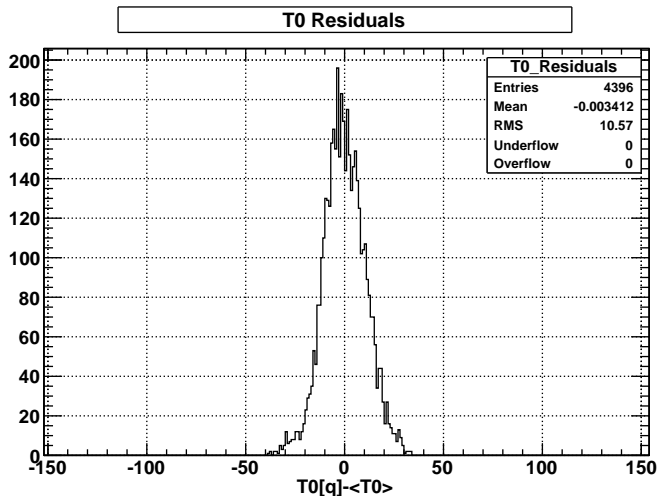
Correction Methodology

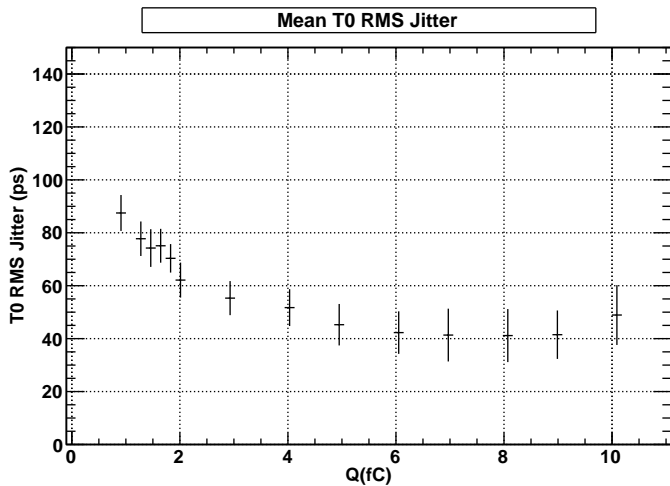
- ▶ non-flat k vs phase means that the correction depends on where the hit falls
- ▶ a 2 stage correction yields better T'_0 reconstruction
 - ▶ correct with an initial (phase independent) estimate
 - ▶ use estimated phase to refine T'_0 correction

T'_0 Transfer Curve

T'_0 Jitter

T'_0 vs Q: Single Phase

T_0' : Systematic Residuals: All Qs and phases

T'_0 : Average Random Jitter vs Q

Summary

- ▶ Synchronisation between clock generator and two pulse generators
 - ▶ reset and charge injection well defined relative to clock
 - ▶ phase of charge injection relative to clock investigated
 - ▶ steps of 10 ps
 - ▶ standard 1-10fC charge range used
- ▶ The Q-invariant quantity T'_0 defined and measured
 - ▶ two sets of 10000 time stamps taken
 - ▶ statistical independence between calibration set and measurement set
 - ▶ two stage T'_0 used
 - ▶ spline parameterisation of k used to give continuous mapping from discrete measurements
- ▶ T'_0 vs Q shown with two contributions
 - ▶ residual systematic timewalk
 - ▶ distribution width estimated to be 10 ps RMS
 - ▶ random jitter
 - ▶ variation due to phase measured
 - ▶ expectation values and distribution widths shown
 - ▶ ~ 60 ps at 2.4fC